|  | Fluid density, <br> $\mathbf{k g} / \mathbf{m}^{\mathbf{3}}$ | Relative fluid <br> velocity, $\mathbf{m ~ s}^{\mathbf{- 1}}$ | Length <br> $\mathbf{s c a l e}, \mathbf{m}$ | Dynamic <br> $\mathbf{v i s c o s i t y ,}$ <br> $\mathbf{N s} / \mathbf{m}^{2}$ | Re, <br> unitless |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Human/air | 1.225 | 1 | 1 | $18 \mathrm{E}-6$ | $\approx 68 \mathrm{E} 3$ |
| Fly/air | 1.225 | $30 \mathrm{E}-3$ | $2 \mathrm{E}-3$ | $18 \mathrm{E}-6$ | $\approx 4$ |
| Human/honey | 1450 | $30 \mathrm{E}-3$ | 1 | 14 | $\approx 3$ |

Table S1: Reynolds numbers of different animals walking through different fluids. The viscosity of air to a fly walking at $30 \mathrm{~mm} \mathrm{~s}^{-1}$ is like the viscosity of honey to a human walking at the same speed. In such a scenario, a person would not be able to make ballistic motions due to the damping from the viscous honey. By the same logic, walking in fruit flies is hardly a dynamic motion; instead, it is dominated by viscous forces from the air and elastic forces from its muscles.


Figure S1: Distribution of contralateral phase relationships $\phi_{C}$ at walking speeds below 5 BL $\mathrm{s}^{-1}$. Instead of a bimodal distribution, whose peaks would be centered at around $1 / 3$ and $2 / 3$, contralateral phases at low and intermediate walking speeds cluster around 0.5 . This indicates anti-phasic stepping in contralateral legs of the same segment. Idealized tetrapod coordination ( $\phi_{C}=1 / 3$ or $2 / 3$ ) is observed rarely.

