



Fig. S1. Mechanical power (N=21) from subareas of the foot: distal-to-hindfoot (solid lines) and summed midtarsal joint and distal-to-forefoot (dashed lines). After the center-of-pressure (COP) moves anterior to the midtarsal joint (denoted by the vertical lines), the magnitude of distal-to-hindfoot power is similar to the summation of midtarsal joint and distal-to-forefoot powers.

Table S1: Distal-to-Hindfoot Work during Stance

| | | Un-normalized (J) | Body Mass (J/kg) | Body Mass + Added Mass (J/kg) |
|--------------------------|---------------|---------------------------------|-----------------------------------|-------------------------------------|
| | Added Mass | mean ± std.d | | |
| Negative Work | %0 | -8.0549 ± 3.5831 [*] | -0.0982 ± 0.0354 ^{**} | -0.0982 ± 0.0355 |
| | %15 | -8.1254 ± 3.8319 ⁺ | -0.0972 ± 0.0310 ⁺⁺ | -0.0865 ± 0.0273 |
| | %30 | -9.2261 ± 4.2079 ^{*,+} | -0.1122 ± 0.0379 ^{**,++} | -0.0885 ± 0.0299 |
| Positive Work | %0 | 4.6847 ± 2.2115 ^{¥,} | 0.0557 ± 0.0228 ^{¥¥} | 0.0557 ± 0.0228 |
| | %15 | 5.3558 ± 2.2739 [¥] | 0.0641 ± 0.0237 | 0.0571 ± 0.0213 |
| | %30 | 5.7480 ± 2.6823 | 0.0682 ± 0.0260 ^{¥¥} | 0.0538 ± 0.0204 |
| Net Work | %0 | -3.3702 ± 3.9143 | -0.0425 ± 0.0453 | -0.0425 ± 0.0453 |
| | %15 | -2.7696 ± 4.2325 | -0.0331 ± 0.0457 | -0.0294 ± 0.0406 |
| | %30 | -3.4780 ± 4.6964 | -0.0439 ± 0.0498 | -0.0347 ± 0.0392 |

* p = 0.029 || +p = 0.013 || ** p = 0.023 || ++ p = 0.027 || ¥ p = 0.032 || || p < 0.001 || ¥¥ p < 0.001

Table S2: Distal-to-Hindfoot Work when COP was posterior to midtarsal joint

| | | Un-normalized (J) | Body Mass (J/kg) | Body Mass + Added Mass (J/kg) |
|--------------------------|---------------|------------------------------|------------------------------|-------------------------------------|
| | Added Mass | mean ± std.d | | |
| Negative Work | %0 | -3.2841±0.9121 [*] | -0.0400±0.0079 ⁺ | -0.0400±0.0079 |
| | %15 | -3.4870±0.8901 | -0.0424±0.0089 | -0.0378±0.0081 |
| | %30 | -3.8335±0.7988 [*] | -0.0473±0.0106 ⁺ | -0.0378±0.0086 |
| Positive Work | %0 | 0.2957±0.2264 | 0.0036±0.0028 | 0.0036±0.0028 |
| | %15 | 0.3398±0.3470 | 0.0041±0.0040 | 0.0036±0.0035 |
| | %30 | 0.3571±0.3288 | 0.0043±0.0036 | 0.0034±0.0029 |
| Net Work | %0 | -2.9884±0.9121 ^{**} | -0.0363±0.0082 ⁺⁺ | -0.0363±0.0082 |
| | %15 | -3.1472±0.8668 | -0.0384±0.0093 | -0.0342±0.0085 |
| | %30 | -3.4763±0.7583 ^{**} | -0.0431±0.0106 ⁺⁺ | -0.0340±0.0085 |

* p = 0.006 || ⁺p = 0.013 || ^{**}p = 0.011 || ⁺⁺p = 0.021

Table S3: Distal-to-Hindfoot Work when COP was anterior to midtarsal joint

| | | Un-normalized (J) | Body Mass (J/kg) | Body Mass + Added Mass (J/kg) |
|--------------------------|---------------|------------------------------|-----------------------------|-------------------------------------|
| | Added Mass | mean ± std.d | | |
| Negative Work | %0 | -4.7708±3.4361 | -0.0582±0.0354 | -0.0582±0.0354 |
| | %15 | -4.6389±3.4015 | -0.0548±0.0300 | -0.0487±0.0264 |
| | %30 | -5.3926±3.9707 | -0.0648±0.0367 | -0.0512±0.0288 |
| Positive Work | %0 | 4.3890±2.1484 ^{*,+} | 0.0520±0.0221 ^{**} | 0.0520±0.0221 |
| | %15 | 5.0159±2.1225 [*] | 0.0600±0.0219 | 0.0535±0.0197 |
| | %30 | 5.3909±2.5230 ⁺ | 0.0640±0.0242 ^{**} | 0.0504±0.1900 |
| Net Work | %0 | -0.3818±3.9544 | -0.0062±0.0447 | -0.0062±0.0447 |
| | %15 | 0.3770±4.0165 | 0.0052±0.0438 | 0.0048±0.0390 |
| | %30 | -0.0017±4.7473 | -0.0009±0.0493 | -0.0007±0.0387 |

* p = 0.040 || ⁺p < 0.001 || ^{**}p < 0.001

Table S4: Midtarsal 6DOF Joint Work during Stance

| | | Un-normalized (J) | Body Mass (J/kg) | Body Mass + Added Mass (J/kg) |
|--------------------------|---------------|-------------------------------|--------------------------------|-------------------------------------|
| | Added Mass | mean ± std.d | | |
| Negative Work | %0 | -4.0015±3.2081 | -0.0478±0.0338 | -0.0478±0.0338 |
| | %15 | -3.8525±3.3856 | -0.0443±0.0290 | -0.0393±0.0255 |
| | %30 | -4.3935±3.4278 | -0.0523±0.0321 | -0.0413±0.0253 |
| Positive Work | %0 | 9.0485±3.7998 ^{*,+} | 0.1078±0.0350 ^{++,¥} | 0.1078±0.0350 ^{¥¥} |
| | %15 | 9.8870±3.7135 ^{**,*} | 0.1183±0.0353 ^{++,} | 0.1053±0.0314 |
| | %30 | 10.5160±3.8066 ^{***} | 0.1262±0.0385 ^{¥,} | 0.0995±0.0304 ^{¥¥,} |
| Net Work | %0 | 5.0470±3.5946 ^{•,♦} | 0.0600±0.0425 ^{••} | 0.0600±0.0425 |
| | %15 | 6.0345±3.5088 [•] | 0.0740±0.0430 | 0.0660±0.0384 |
| | %30 | 6.1231±4.1247 [♦] | 0.0739±0.0494 ^{••} | 0.0582±0.03884 |

* p = 0.001 || +p < 0.001 || **p = 0.039 || ++ p < 0.001 || ¥p < 0.001 || || p = 0.028 || ¥¥p = 0.029
 || ||| p = 0.040 || • p = 0.041 || ♦ p = 0.028 || •• p = 0.025

Table S5: Distal-to-Forefoot Work during Stance

| | | Un-normalized (J) | Body Mass (J/kg) | Body Mass + Added Mass (J/kg) |
|------------------|---------------|----------------------|---------------------|-------------------------------------|
| | Added Mass | | mean ± std.d | |
| | %0 | -6.1855±3.1207 | -0.0755±0.0352 | -0.0755±0.0352 |
| Negative Work | %15 | -6.5815±2.9982* | -0.0769±0.0297 | -0.0709±0.0263 |
| | %30 | -7.1175±3.0964* | -0.0864±0.0316 | -0.0682±0.0250 |
| | %0 | 0.8085±0.5474**,+ | 0.0095±0.0057++,¥ | 0.0095±0.0057 |
| Positive Work | %15 | 0.9920±0.5826** | 0.0117±0.0052++ | 0.0104±0.0046 |
| | %30 | 1.1270±0.7161+ | 0.0129±0.0061¥ | 0.0102±0.0048 |
| | %0 | -5.3765±3.3617 | -0.0660±0.0385 | -0.0660±0.0385 |
| Net Work | %15 | -5.5895±3.1781 | -0.0680±0.0328 | -0.0605±0.0290 |
| | %30 | -5.9905±3.1358 | -0.0735±0.0337 | -0.0580±0.0267 |

* p = 0.025 || +p = 0.009 || **p = 0.013 || ++ p = 0.034 || ¥p = 0.006